

TA31QR



Product Segments

Care Motion

The TA31QR improves upon the TA31 with added design benefits and functionality, while providing a high quality yet economical option for medical applications. In particular, the TA31QR provides multiple output signal options. These include a spindle set Hall sensors or POT which will continue to send position feedback after the quick release action is performed. This feature allows the user to maintain accurate position within the control system without having to perform a system reset.

General Features

Max. load 5,000N (push); 3,000N (pull)

Max. speed at max. load 4.9mm/s
Max. speed at no load 11.2mm/s

Retracted length ≥ Stroke + 178mm

IP rating IP66W Stroke 25~450mm

Output signals Hall sensors, POT, spindle set Hall sensors
Options Multiple functions for spindle sub-assembly

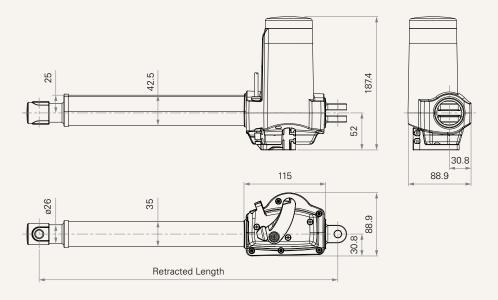
Voltage 12/24V DC, 12/24V DC (PTC)

Color Black or grey Operational temperature range $+5^{\circ}\text{C} \sim +45^{\circ}\text{C}$

1

Drawing

Standard Dimensions (mm)



Load	and	Snee	h
LUau	allu	Ohcc	u

CODE	Load (N)	Load (N)		Typical Current (A)		Typical Speed (mm/s)	
	Push	Pull	Force (N)	No Load 32V DC	With Load 24V DC	No Load 32V DC	With Load 24V DC
Motor Speed (3800RPM, Duty Cycle 10%)							
J	3500	3000	3500	0.8	3.4	11.2	6.9
K	5000	3000	5000	0.8	3.7	8.6	4.9

Note

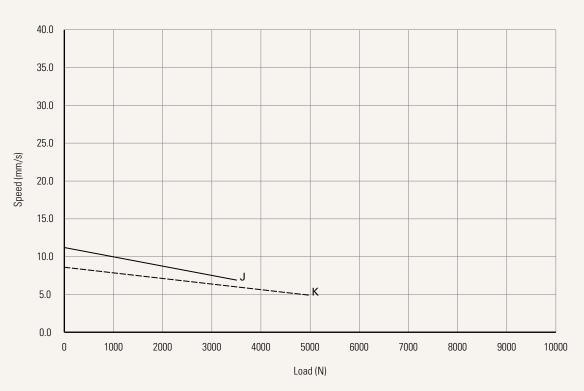
- 1 The current & speed in table are tested with 24V DC motor. With a 12V DC motor, the current is approximately twice the current measured in 24V DC; speed will be similar for both voltages.
- 2 This self-locking force level is reached only when a short circuit is applied on the terminals of the motor. All the TiMOTION control boxes have this feature built-in.
- 3 The current & speed in table are tested when the actuator is extending under push load.



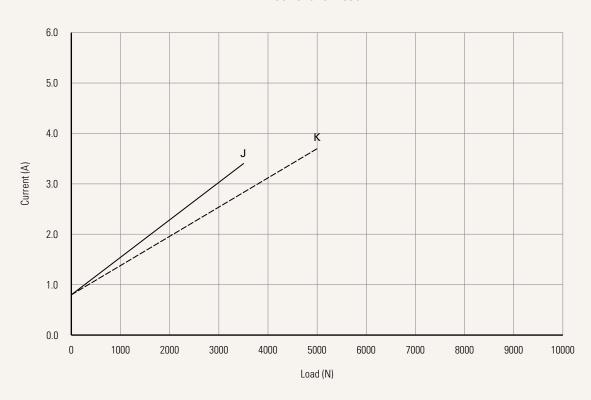
Performance Data (24V DC Motor)

Motor Speed (3800RPM, Duty Cycle 10%)

Speed vs. Load



Current vs. Load



Note

1 The performance data in the curve charts shows theoretical value.



TA31QR Ordering Key



TA31QR

				Version: 20241213-k
Voltage	1 = 12V DC	2 = 24V DC	5 = 24V DC, PTC	6 = 12V DC, PTC
Load and Speed	See page 2			
Stroke (mm)	See page 5			
Retracted Length (mm)	See page 5			
Rear Attachment (mm) See page 6	3 = Aluminum casting, U	clevis, slot 8.2, depth 17.0, hole clevis, slot 8.2, depth 17.0, hole clevis, slot 8.2, depth 17.0, hole	12.2	
Front Attachment (mm) See page 6	2 = Punched hole on inner 3 = Plastic, U clevis, widtl 4 = Plastic, U clevis, widtl 5 = Punched hole on inner 6 = Punched hole on inner 7 = Aluminum casting, U or 8 = Aluminum casting, U or	r tube + plastic cap, without slot r tube + plastic cap, without slot h 8.2, depth 20.0, hole 10.2, for p h 8.2, depth 20.0, hole 12.2, for p r tube, wihout slot, hole 10.2, wi r tube, wihout slot, hole 12.2 clevis, width 6.2, depth 17.0, hol clevis, width 6.2, depth 17.0, hol clevis, width 6.2, depth 17.0, hol	, hole 12.2 oush < 4000N and pull < 250 oush < 4000N and pull < 250 th plastic bush e 10.2 e 12.2	DON
Direction of Rear Attachment (Counterclockwise) See page 7	1 = 0°	3 = 90°		
Color	1 = Black	2 = Pantone 428C		
IP Rating	1 = Without	2 = IP54	3 = IP66	5 = IP66W
Special Functions for Spindle Sub- Assembly	0 = Without (Standard) 1 = Safety nut	2 = Standard push only 3 = Standard push only + Safety nut	B = Cushion C = Cushion+Safety nut	F = Centrifugal G = Centrifugal+Safety nut
Functions for Limit Switches See page 7	1 = Two switches at full retracted / extended positions to cut current 2 = Two switches at full retracted / extended positions to cut current + third one in between to send signal 3 = Two switches at full retracted / extended positions to send signal 4 = Two switches at full retracted / extended positions to send signal + third one in between to send signal 5 = Two switches at full retracted / extended positions to send signal (Operate with control box: TC1, TC8, TC10, TC14, TC21)			
Output Signals	0 = Without 2 = Hall sensor * 2		P = POT H = Spindle set Hall senso	ors * 2
Connector (mm) See page 7-8	1 = DIN 6P, 90° plug 2 = Tinned leads 4 = Big 01P, plug C = Y cable (direct cut, wa D = Extension cable, not p	ter proof, anti-pull) reset on motor cover (cable legth	R = Extension cable, present E = Molex 8P, plug F = DIN 6P, 180° plug G = Audio plug	t on motor cover (cable legth 50)
Cable Length (mm)	0 = Straight, 100 1 = Straight, 500 3 = Straight, 1000 5 = Straight, 1500	6 = Straight, 2000 7 = Curly, 200 8 = Curly, 400 B~H = For direct cut system	legth 120)	reset on motor cover (cable et on motor cover (cable legth

See page 7



Retracted Length (mm)

- 1. Calculate A+B+C+D = Y
- 2. Retracted length needs to \geq Stroke + Y
- *Standard stroke: 25~450mm

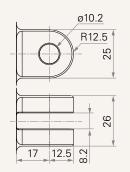
A. Front Attacl	hment				
CODE					
1, 2, 5, 6	+178				
3, 4	+201				
7, 8, 9	+193				
B. Load V.S. St	roke				
Stroke (mm)	Load (N)				
	3500	5000			
25~150	-	-			
151~200	-	-			
201~250	-	-			
251~300	-	-			
301~350	+5	+5			
351~400	+10	+10			
401~450	+15	+15			

CODE	Load (N)	Load (N)				
	3500	5000				
0	-	-				
1	-	-				
2	-	+3				
3	-	+3				
В	+28	-				
С	+28	-				
F	+20	-				
G	+20	-				
D. Signal O	utputs					
CODE						
0	-					
2	-					
P	+7					
Н	-					

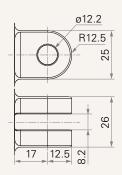


Rear Attachment (mm)

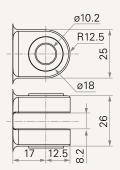
2 = Aluminum casting, U clevis, slot 8.2, depth 17.0, hole 10.2



3 = Aluminum casting, U clevis, slot 8.2, depth 17.0, hole 12.2

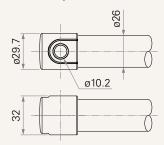


C = Aluminum casting, U clevis, slot 8.2, depth 17.0, hole 10.2, with T-bushing

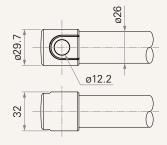


Front Attachment (mm)

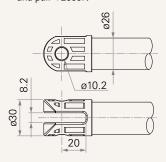
1 = Punched hole on inner tube + plastic cap, without slot, hole 10.2, with plastic bush



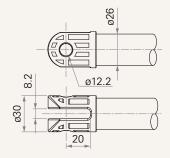
2 = Punched hole on inner tube + plastic cap, without slot, hole 12.2



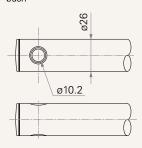
 $3 = Plastic, \, U \, clevis, \, width \, 8.2, \, depth \, 20.0, \, hole \, 10.2, \, for \, push < 4000N \, and \, pull < 2500N$



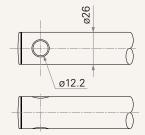
4 = Plastic, U clevis, width 8.2, depth 20.0, hole 12.2, for push < 4000N and pull < 2500N



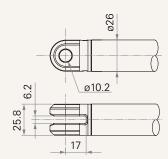
5 = Punched hole on inner tube, wihout slot, hole 10.2, with plastic



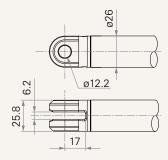
6 = Punched hole on inner tube, wihout slot, hole 12.2



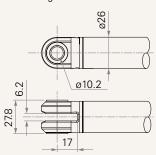
7 = Aluminum casting, U clevis, width 6.2, depth 17.0, hole 10.2



8 = Aluminum casting, U clevis, width 6.2, depth 17.0, hole 12.2



9 = Aluminum casting, U clevis, width 6.2, depth 17.0, hole 10.2, with T-bushing

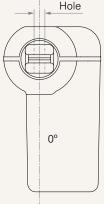


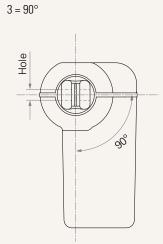


Direction of Rear Attachment (Counterclockwise)









Functions for Limit Switches

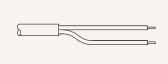
Wire Defin	finitions							
CODE	Pin	Pin						
	1 (Green)	2 (Red)	3 (White)	4 (Black)	5 (Yellow)	6 (Blue)		
1	extend (VDC+)	N/A	N/A	N/A	retract (VDC+)	N/A		
2	extend (VDC+)	N/A	middle switch pin B	middle switch pin A	retract (VDC+)	N/A		
3	extend (VDC+)	common	upper limit switch	N/A	retract (VDC+)	lower limit switch		
4	extend (VDC+)	common	upper limit switch	medium limit switch	retract (VDC+)	lower limit switch		
5	extend (VDC+)	N/A	upper limit switch	common	retract (VDC+)	lower limit switch		

Connector





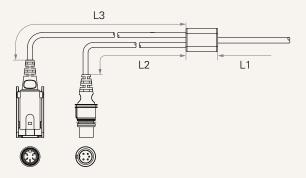




4 = Big 01P, plug



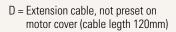
C = Y cable (direct cut, water proof, anti-pull)

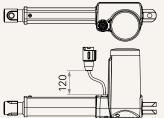


Cable Length for Direct Cut System (mm)					
CODE	L1	L2	L3		
В	100	100	100		
С	100	1000	400		
D	100	2700	500		
E	1000	100	100		
F	100	600	1000		
G	1500	1000	1000		
Н	100	100	1200		



Connector

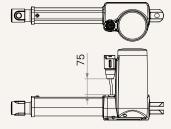




G = Audio plug



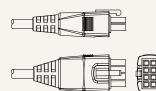
R = Extension cable, preset on motor cover (cable legth 50mm)



Q = Molex 6P, 90° plug



E = Molex 8P, plug



F = DIN 6P, 180° plug



S = Molex 6P, 180°plug

