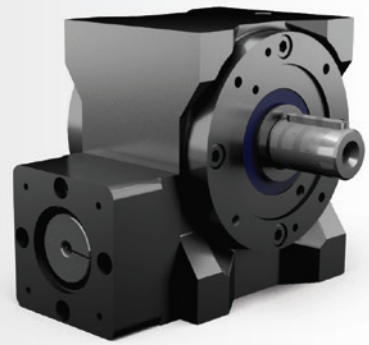


# 11.5 Type SC – Servo worm gearboxes

## 11.5.15 Features

- Gear ratios:  $i = 10:1$  to  $20:1$  ( $i > 26$  upon request)
- Maximum acceleration torques up to  $T_{2B} = 1100 \text{ Nm}$
- 5 gearbox sizes with 040 to 100 mm centre-to-centre distance
- Optimised efficiency
- Minimised circumferential backlash (optional)
- Worm gearboxes with square flange, suitable for fitting servo-motors
- Zero-play three-piece claw coupling



### 11.5.15.1 Models

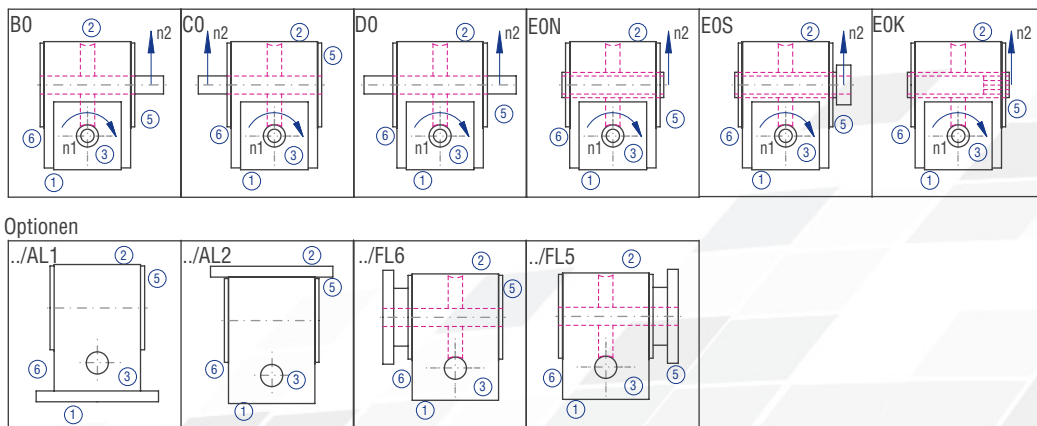


Figure 11.5.15-1; Models

### 11.5.15.2 Gearbox sides

The example shows the Model B0

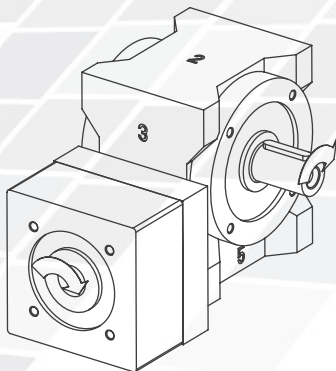


Figure 11.5.15-3; Gearbox sides

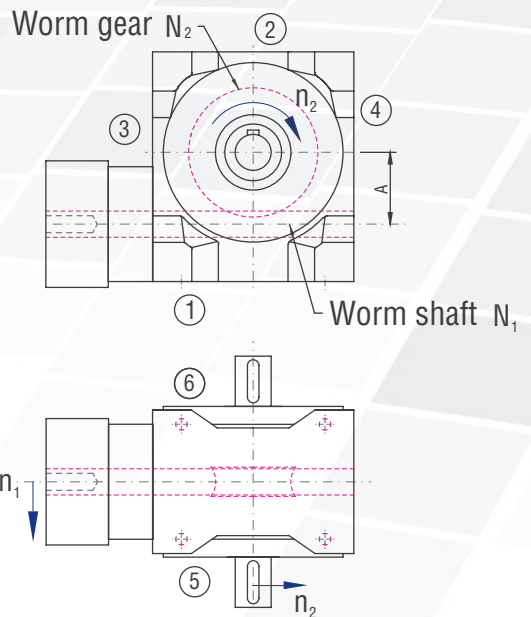


Figure 11.5.15-2; Shaft designs

### 11.5.15.3 Order code

The order code reflects the customer specifications. Example:

Type	Size	Gear ratio	Model	Fixing side	Installation position	Speed $n_2$	Design
SC	050	5:1	B0-	1.	1-	600	/0000
Description	Size; Table 11.5.15-1	Table 11.5.15-1	Figure 11.5.15-1	Side on which fixing is made; Table 11.5.4-1	Side directed downwards; Figure 4.3.1-1 Gearbox sides	Slowly rotating shaft Table 11.5.15-1	Will be determined by ATEK
	V080-		/	14 x 30	No. 301		KN
	Flange			Motor shaft $\varnothing$ x length	Flange no.		See chapter "Coupling"

## 11.5.15.4 Overview of performance data

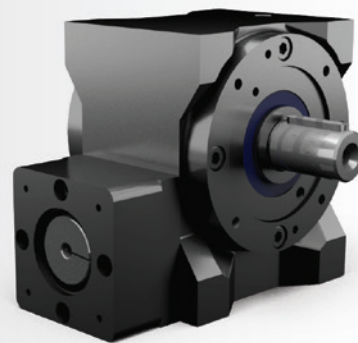
The performance data and torques listed in the selection tables are only valid if the gearboxes are used in the installation positions 1, 5 or 6. If the worm shaft is vertical or located at the top (installation position 3, 4 or 2), 90% of the values specified must be expected.

Please enquire other gear ratios.

i(-)	n <sub>1</sub> [1/min]	i <sub>ist</sub>	n <sub>2</sub> [1/min]	040	050	063	080	100
				T <sub>2N</sub> [Nm]	T <sub>2N</sub> [Nm]	T <sub>2N</sub> [Nm]	T <sub>2N</sub> [Nm]	T <sub>2N</sub> [Nm]
10:1	4000	38:4	421		70,0			
		39:4	410	32,0		101,0		
		40:4	400				132,0	195,0
	3000	38:4	316		83,0			
		39:4	308	37,0		124,0		
		40:4	300				177,0	257,0
	2400	38:4	253		97,0			
		39:4	246	42,0		148,0		
		40:4	240				222,0	318,0
	1500	38:4	158		110,0			
		39:4	154	48,0		171,0		
		40:4	150				267,0	380,0
20:1	4000	38:2	211		72,0			
		39:2	205	36,0		116,0		
		40:2	200				153,0	236,0
	3000	38:2	158		85,0			
		39:2	154	41,0		141,0		
		40:2	150				203,0	308,0
	2400	38:2	126		98,0			
		39:2	123	46,0		166,0		
		40:2	120				253,0	380,0
	1500	38:2	79		111,0			
		39:2	77	51,0		190,0		
		40:2	75				303,0	452,0

	040	050	063	080	100
T <sub>2B</sub> (S5) [Nm]	50	112	216	408	1006
T <sub>2Not</sub> (S5) [Nm]	77	152	306	625	1090
N <sub>1 max</sub> [U/min]	6000	5500	5000	4500	3200
T <sub>2B</sub> (S5) [Nm]	58	133	259	498	1112
T <sub>2Not</sub> (S5) [Nm]	90	179	355	725	1440
N <sub>1 max</sub> [U/min]	6500	5500	5000	4500	3200

Table 11.5.15-1



## Characteristics

Characteristic	Standard	Option
<b>Toothing</b>	Hardened and ground worm shaft / bronze worm gear	See chapter 11.5.2
<b>Gear ratio</b>	10:1 to 20:1	
<b>Housing / Flanges</b>	Grey cast iron / aluminium	
<b>Threaded mounting holes</b>	On gearbox side 1 and on the flanges	See chapter 11.5.4
<b>Shaft</b>	Material 1 C45, shaft ends greased Fit with ISO j6 tolerance with parallel keyway: according to DIN 6885 Sheet 1	See chapter 4.6.2
<b>Hollow shaft</b>	Material 1 C45, shafts greased Fit with ISO H7 tolerance with parallel keyway: according to DIN 6885 Sheet 1	See chapter 4.6.3
<b>Radial shaft seal ring</b>	NBR, form A	See chapter 4.8
<b>Ambient temperature</b>	-10°C to +90°C. The values of the performance tables are valid for +20°C	See chapter 4.9.3
<b>Circumferential backlash</b>	< 20 arcmin	See chapter 11.5.11
<b>Protection class</b>	IP 54	See chapter 4.5
<b>Corrosion protection</b>	Prime coat; layer thickness > 40 µm	See chapter 4.4.1
<b>Bearing life L10h</b>	more than 15,000h	See chapter 4.9.1
<b>Oil change intervals</b>	Not required if the oil temperature is kept < 90°C The lifetime of the bearings can be increased by the factor 1.5 if the oil is changed after the first 500 service hours and then every 5000 service hours.	See chapter 11.5.9
<b>Lubricants</b>	Synthetic lubricants	See chapter 11.5.9
<b>Motor flange</b>	Aluminium	See chapter 11.5.14
<b>Coupling</b>	Insertable, flexible claw coupling, suitable for servo-motors For smooth motor shafts      clamping hub For smooth motor shafts      tension ring hub For motor shafts with parallel key clamping hub with groove	KN SN KNN See chapter 11.5.13

## Torques in operating mode S1

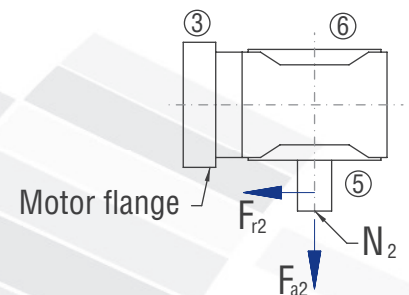
I rated I ist	10:1		20:1	
	$n_2$ [1/min]	$T_{2N}$ [Nm]	$n_2$ [1/min]	$T_{2N}$ [Nm]
4000	410	32	205	36
3000	308	37	154	41
2400	246	42	123	46
1500	154	48	77	51

## Torques in operating mode S5

Coupling size	d [mm]	I rated $T_{2N}$ [Nm] $n_{1max}$ [U/min]	10:1		20:1	
			KN	KNN/SN	KN	KNN/SN
K14	9	$T_{2B}$ [Nm]	50,0	50,0	58,0	58,0
		$T_{2NOT}$ [Nm]	68,3	77,0	90,0	90,0
	11	$T_{2B}$ [Nm]	50,0	50,0	58,0	58,0
		$T_{2NOT}$ [Nm]	77,0	77,0	90,0	90,0
	14	$T_{2B}$ [Nm]	50,0	50,0	58,0	58,0
		$T_{2NOT}$ [Nm]	77,0	77,0	90,0	90,0
16	$T_{2B}$ [Nm]	50,0	50,0	58,0	58,0	
	$T_{2NOT}$ [Nm]	77,0	77,0	90,0	90,0	
K19	9	$T_{2B}$ [Nm]	50,0	50,0	58,0	58,0
		$T_{2NOT}$ [Nm]	77,0	77,0	90,0	90,0
	11	$T_{2B}$ [Nm]	50,0	50,0	58,0	58,0
		$T_{2NOT}$ [Nm]	77,0	77,0	90,0	90,0
	14	$T_{2B}$ [Nm]	50,0	50,0	58,0	58,0
		$T_{2NOT}$ [Nm]	77,0	77,0	90,0	90,0
	16	$T_{2B}$ [Nm]	50,0	50,0	58,0	58,0
		$T_{2NOT}$ [Nm]	77,0	77,0	90,0	90,0
	19	$T_{2B}$ [Nm]	50,0	50,0	58,0	58,0
		$T_{2NOT}$ [Nm]	77,0	77,0	90,0	90,0
	24	$T_{2B}$ [Nm]	50,0	50,0	58,0	58,0
		$T_{2NOT}$ [Nm]	77,0	77,0	90,0	90,0

## Permissible radial force $F_{r2}$ and axial force $F_{a2}$ on shaft $N_2$

$n_2$ [rpm]	200		125		75		50		30		10	
$T_2$ [Nm]	$F_r$ [N]	$F_a$ [N]	$F_r$ [N]	$F_a$ [N]	$F_r$ [N]	$F_a$ [N]	$F_r$ [N]	$F_a$ [N]	$F_r$ [N]	$F_a$ [N]	$F_r$ [N]	$F_a$ [N]
< 80	970	485	1250	625	1380	690	1600	800	1800	900	2500	1250



Servo gearboxes  
(precision gearboxes)

## Gearbox inertia moments/mass

Inertia moment  $J_1$  related to the fast-rotating shaft ( $N_1$ )

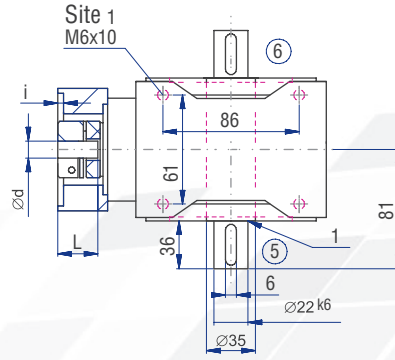
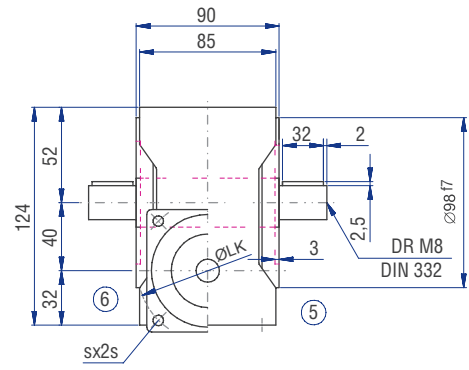
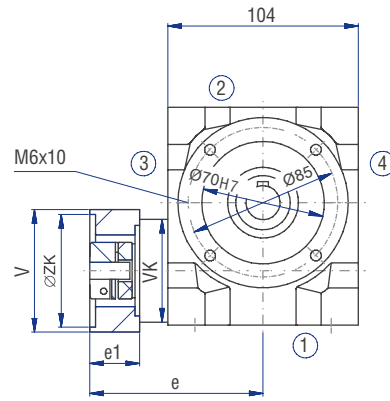
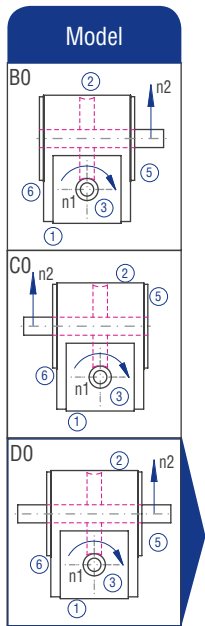
i rated [-]	Inertia moment [kgcm <sup>2</sup> ]							Mass ca. [kg]
	5:1	7.5:1	10:1	13:1	15:1	20:1	26:1	
$J$ [kgcm <sup>2</sup> ]	0.3307	0.2454	0.1801	0.1458	0.1943	0.1476	0.1268	7

## Inertia moment Coupling J

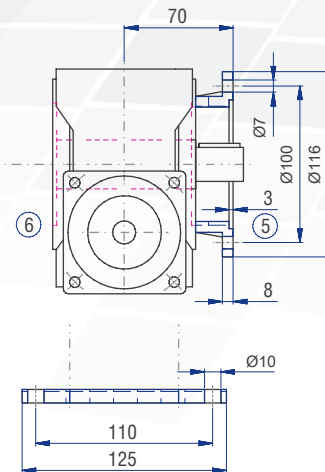
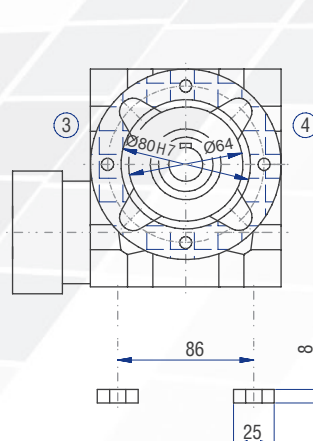
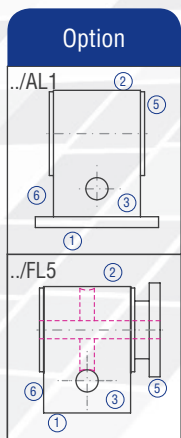
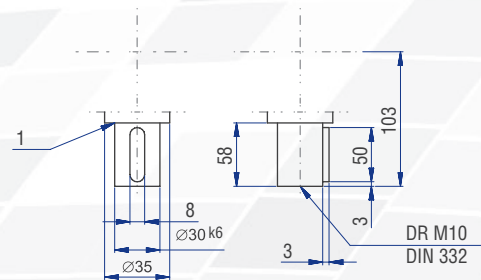
	Inertia moment [kgcm <sup>2</sup> ]		
	KN J [kgcm <sup>2</sup> ]	KNN J [kgcm <sup>2</sup> ]	SN J [kgcm <sup>2</sup> ]
K14	0.0606	0.0606	0.1446
K19	0.4229	0.4229	0.6349

The mass of the gearbox may deviate depending on the flange size and the gear ratio.

# 11.5.16 Type SC 040 – Servo worm gearboxes



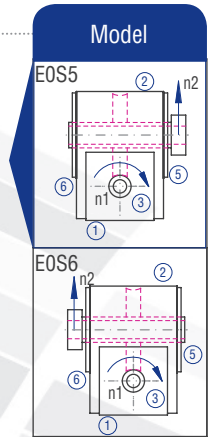
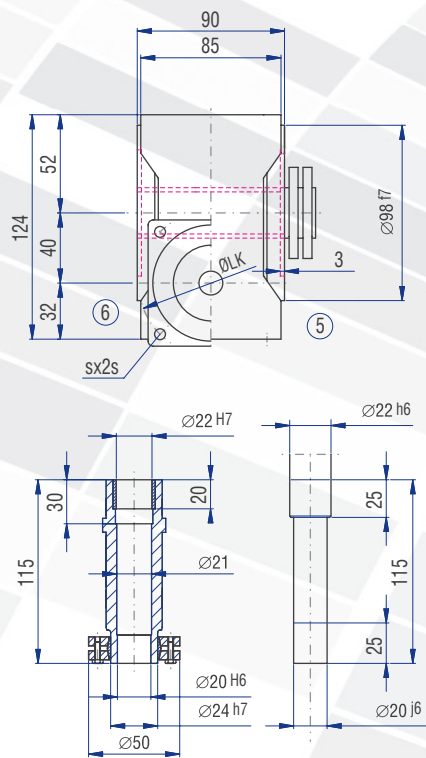
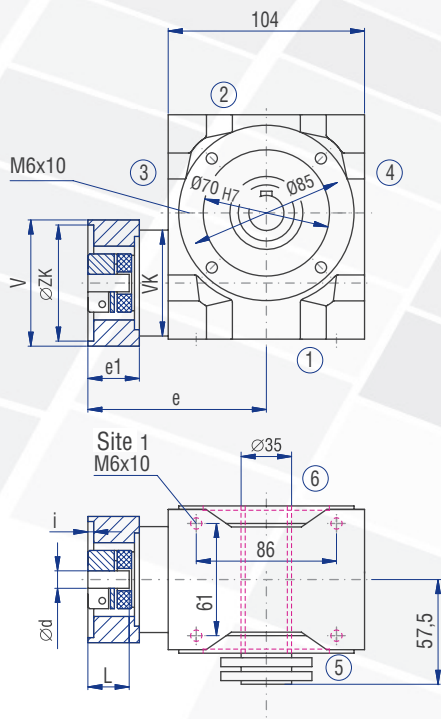
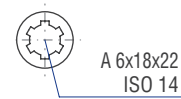
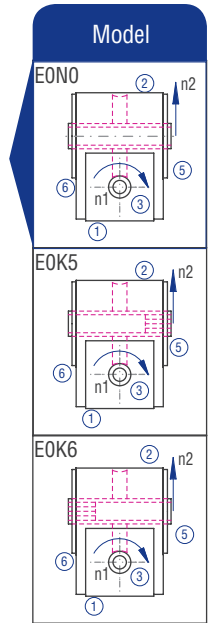
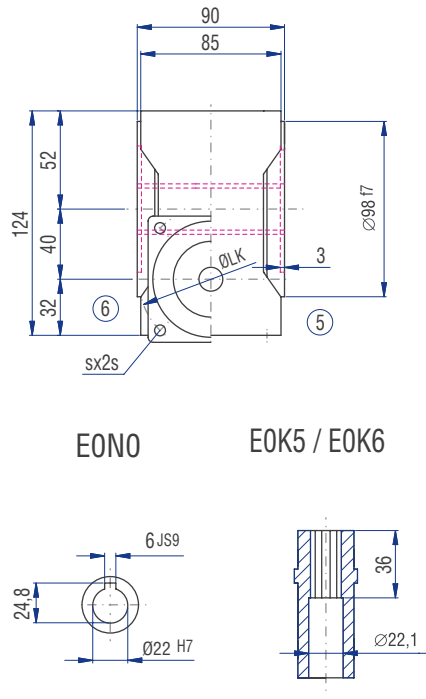
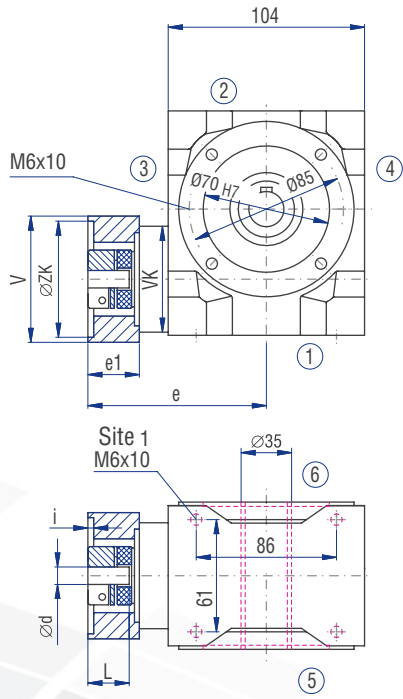
## Implementation VV



## Motor dimensions

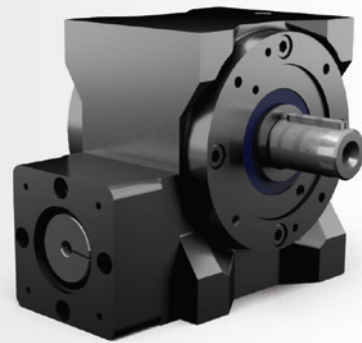
Flange no.	Motor shaft (dxL)	Thread (s)	V [mm]	ZK [mm]	LK [mm]	i [mm]	e [mm]	e1 [mm]
001	11*23	M4	65	40	63	3	93.0	30.0
002	11*23	M5	65	40	63	3	93.0	30.0
102	11*23	M5	65	60	75	3	90.0	26.5
202	11*23	M5	65	60	90	4	90.0	26.5
103	14*30	M6	65	60	75	3	108.5	45.0
104	14*30	M5	65	60	75	3	108.5	45.0
201	14*30	M5	65	60	90	4	108.5	45.0
301	14*30	M6	65	50	95	4	108.5	45.0
401	14*30	M6	65	80	100	4	108.5	45.0
501	14*30	M8	65	95	115	4	108.5	45.0
601	19*40	M8	90	95	130	4	121.0	45.0
611	19*40	M8	90	110	130	5	121.0	45.0
701	19*40	M8	90	110	145	5	121.0	45.0
802	19*40	M10	90	110	165	5	121.0	45.0

The dimensions e and e1 will change for the coupling type "clamping hub with groove" (KNN). Please contact us for consultation!



Servo gearboxes  
(precision gearboxes)





## Characteristics

Characteristic	Standard	Option
<b>Toothing</b>	Hardened and ground worm shaft / bronze worm gear	See chapter 11.5.2
<b>Gear ratio</b>	10:1 to 20:1	
<b>Housing / Flanges</b>	Grey cast iron / aluminium	
<b>Threaded mounting holes</b>	On gearbox side 1 and on the flanges	See chapter 11.5.4
<b>Shaft</b>	Material 1 C45, shaft ends greased Fit with ISO j6 tolerance with parallel keyway: according to DIN 6885 Sheet 1	See chapter 4.6.2
<b>Hollow shaft</b>	Material 1 C45, shafts greased Fit with ISO H7 tolerance with parallel keyway: according to DIN 6885 Sheet 1	See chapter 4.6.3
<b>Radial shaft seal ring</b>	NBR, form A	See chapter 4.8
<b>Ambient temperature</b>	-10°C to +90°C. The values of the performance tables are valid for +20°C	See chapter 4.9.3
<b>Circumferential backlash</b>	< 20 arcmin	See chapter 11.5.11
<b>Protection class</b>	IP 54	See chapter 4.5
<b>Corrosion protection</b>	Prime coat; layer thickness > 40 µm	See chapter 4.4.1
<b>Bearing life L10h</b>	more than 15,000h	See chapter 4.9.1
<b>Oil change intervals</b>	Not required if the oil temperature is kept < 90°C The lifetime of the bearings can be increased by the factor 1.5 if the oil is changed after the first 500 service hours and then every 5000 service hours.	See chapter 11.5.9
<b>Lubricants</b>	Synthetic lubricants	See chapter 11.5.9
<b>Motor flange</b>	Aluminium	See chapter 11.5.14
<b>Coupling</b>	Insertable, flexible claw coupling, suitable for servo-motors For smooth motor shafts      clamping hub      KN For smooth motor shafts      tension ring hub      SN For motor shafts with parallel key clamping hub with groove      KNN	See chapter 11.5.13

## Torques in operating mode S1

I rated I ist	10:1		20:1	
	$n_2$ [1/min]	$T_{2N}$ [Nm]	$n_2$ [1/min]	$T_{2N}$ [Nm]
4000	421	70	211	72
3000	316	83	158	85
2400	253	97	126	98
1500	158	110	79	111

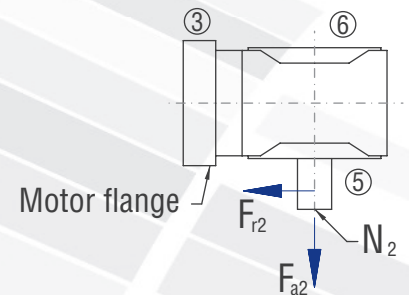
## Torques in operating mode S5

Coupling size	d [mm]	I rated $T_{2N}$ [Nm] $n_{1max}$ [U/min]	10:1		20:1	
			KN	KNN/SN	KN	KNN/SN
K19	9	$T_{2B}$ [Nm]	112,0		133,0	
		$T_{2NOT}$ [Nm]	152,0		179,0	
	11	$T_{2B}$ [Nm]	112,0	112,0	133,0	133,0
		$T_{2NOT}$ [Nm]	152,0	152,0	179,0	179,0
	14	$T_{2B}$ [Nm]	112,0	112,0	133,0	133,0
		$T_{2NOT}$ [Nm]	152,0	152,0	179,0	179,0
	16	$T_{2B}$ [Nm]	112,0	112,0	133,0	133,0
		$T_{2NOT}$ [Nm]	152,0	152,0	179,0	179,0
	19	$T_{2B}$ [Nm]	112,0	112,0	133,0	133,0
		$T_{2NOT}$ [Nm]	152,0	152,0	179,0	179,0
	24	$T_{2B}$ [Nm]	112,0		133,0	
		$T_{2NOT}$ [Nm]	152,0		179,0	
K24	11	$T_{2B}$ [Nm]	112,0	112,0	133,0	133,0
		$T_{2NOT}$ [Nm]	152,0	0,0	179,0	0,0
	14	$T_{2B}$ [Nm]	112,0	112,0	133,0	133,0
		$T_{2NOT}$ [Nm]	152,0	152,0	179,0	179,0
	16	$T_{2B}$ [Nm]	112,0	112,0	133,0	133,0
		$T_{2NOT}$ [Nm]	152,0	152,0	179,0	179,0
	19	$T_{2B}$ [Nm]	112,0	112,0	133,0	133,0
		$T_{2NOT}$ [Nm]	152,0	152,0	179,0	179,0
	24	$T_{2B}$ [Nm]	112,0	112,0	133,0	133,0
		$T_{2NOT}$ [Nm]	152,0	152,0	179,0	179,0
	28	$T_{2B}$ [Nm]	112,0	112,0	133,0	133,0
		$T_{2NOT}$ [Nm]	152,0	152,0	179,0	179,0

Servo gearboxes  
(precision gearboxes)

## Permissible radial force $F_{r2}$ and axial force $F_{a2}$ on shaft $N_2$

$n_2$ [rpm]	200		125		75		50		30		10	
$T_2$ [Nm]	$F_r$ [N]	$F_a$ [N]	$F_r$ [N]	$F_a$ [N]	$F_r$ [N]	$F_a$ [N]	$F_r$ [N]	$F_a$ [N]	$F_r$ [N]	$F_a$ [N]	$F_r$ [N]	$F_a$ [N]
< 120	2000	1000	2400	1200	2850	1425	3350	1675	4000	2000	4800	2400
> 120	1540	770	1850	925	2190	1095	2580	1290	3080	1540	3700	1850



## Gearbox inertia moments/mass

Inertia moment  $J_1$  related to the fast-rotating shaft ( $N_1$ )

i rated [-]	Inertia moment [kgcm <sup>2</sup> ]						
	5:1	7.5:1	10:1	13:1	15:1	20:1	26:1
$J$ [kgcm <sup>2</sup> ]	0.9509	0.7327	0.5820	0.4876	0.6017	0.4996	0.4375

Mass ca. [kg]
13

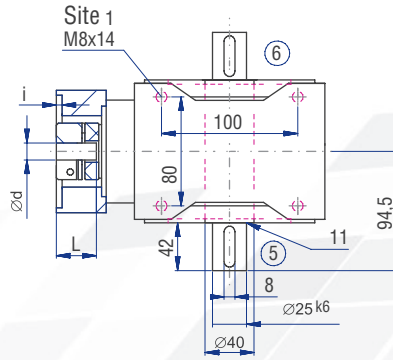
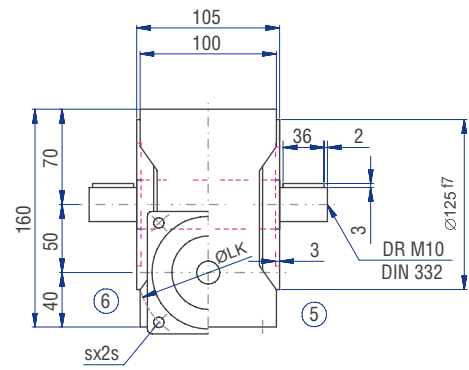
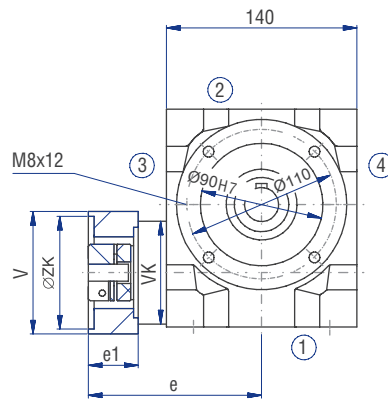
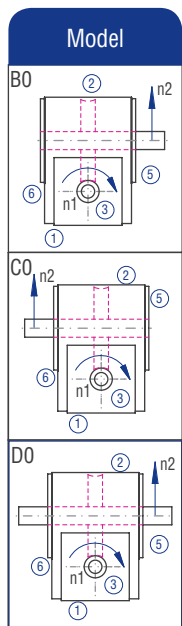
## Inertia moments Coupling J

	KN	KNN	SN
	J [kgcm <sup>2</sup> ]	J [kgcm <sup>2</sup> ]	J [kgcm <sup>2</sup> ]
K19	0.4229	0.4229	0.6349
K24	1.0910	1.0910	2.7750

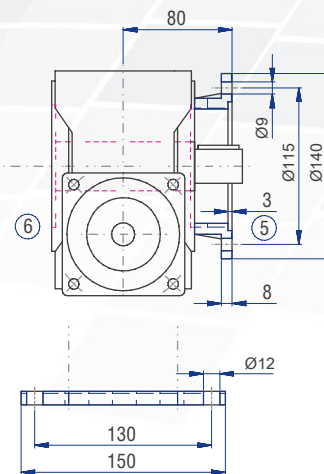
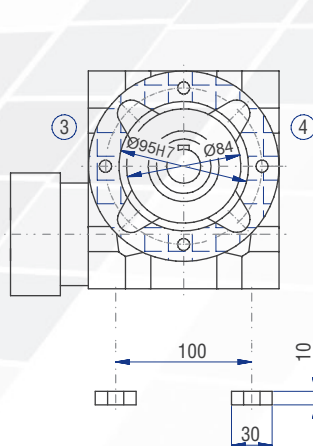
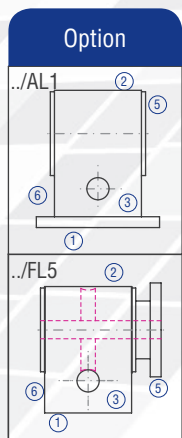
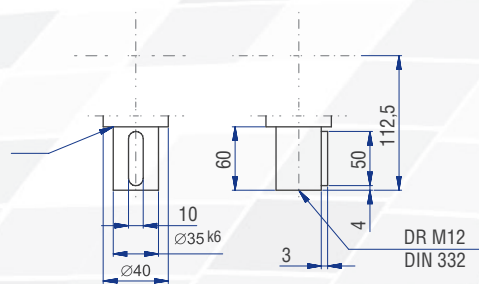
The mass of the gearbox may deviate depending on the flange size and the gear ratio.



# 11.5.17 Type SC 050 – Servo worm gearboxes



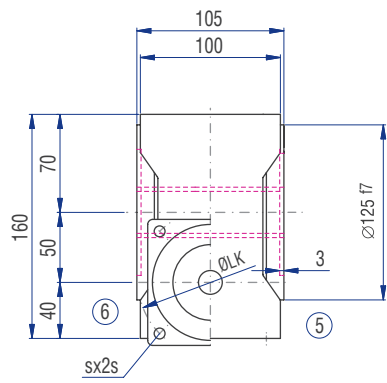
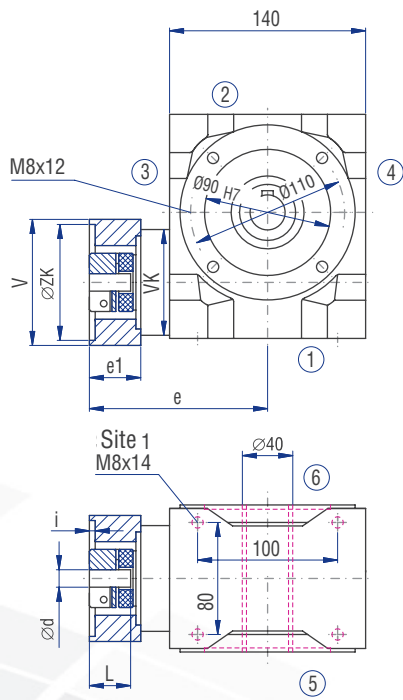
## Implementation VV



## Motor dimensions

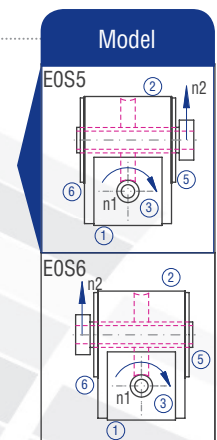
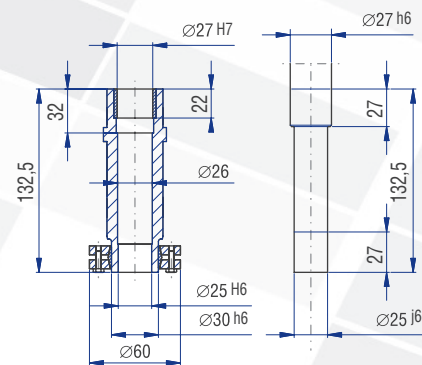
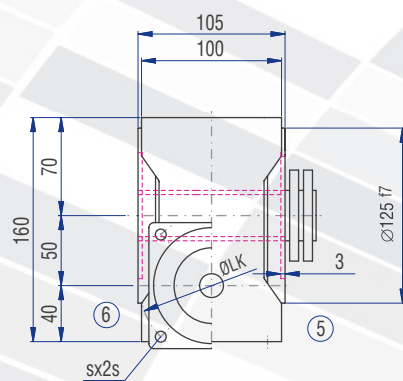
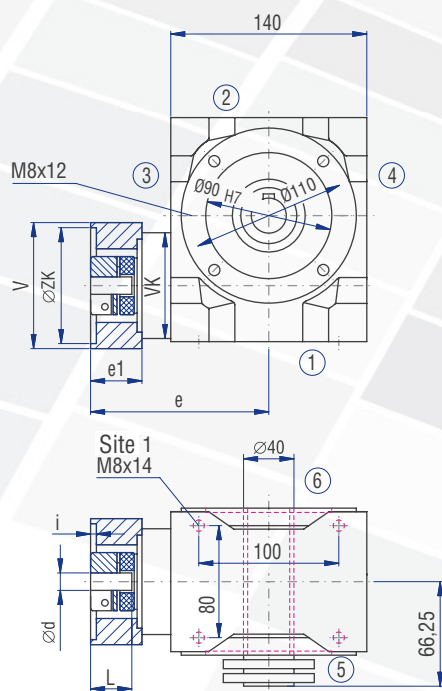
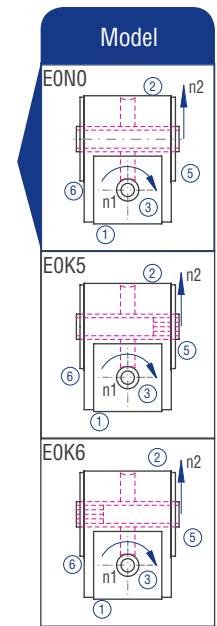
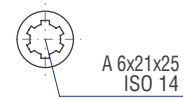
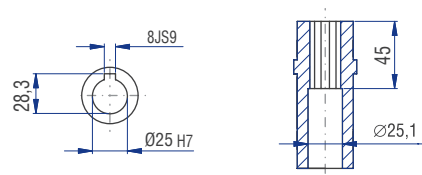
Flange no.	Motor shaft (dxL)	Thread (s)	V [mm]	ZK [mm]	LK [mm]	i [mm]	e [mm]	e1 [mm]
103	19*40	M6	90	60	75	3	141.0	45.0
201	19*40	M5	90	60	90	3	141.0	45.0
301	19*40	M6	90	50	95	4	141.0	45.0
401	19*40	M6	90	80	100	4	141.0	45.0
501	19*40	M8	90	95	115	4	141.0	45.0
601	19*40	M8	90	95	130	4	141.0	45.0
611	19*40	M8	90	110	130	5	141.0	45.0
701	19*40	M8	90	110	145	5	141.0	45.0
802	19*40	M10	90	110	165	5	141.0	45.0
811	24*50	M10	120	130	165	5	155.0	54.0

The dimensions e and e1 will change for the coupling type "clamping hub with groove" (KNN). Please contact us for consultation!

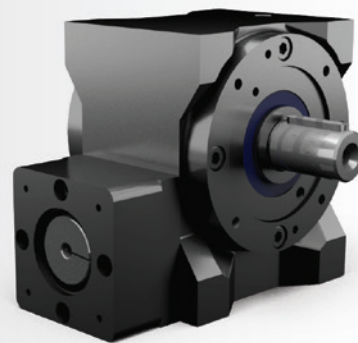


EON0

EOK5 / EOK6



Servo gearboxes  
(precision gearboxes)



## Characteristics

Characteristic	Standard	Option
<b>Toothing</b>	Hardened and ground worm shaft / bronze worm gear	See chapter 11.5.2
<b>Gear ratio</b>	10:1 to 20:1	
<b>Housing / Flanges</b>	Grey cast iron / aluminium	
<b>Threaded mounting holes</b>	On gearbox side 1 and on the flanges	See chapter 11.5.4
<b>Shaft</b>	Material 1 C45, shaft ends greased Fit with ISO j6 tolerance with parallel keyway: according to DIN 6885 Sheet 1	See chapter 4.6.2
<b>Hollow shaft</b>	Material 1 C45, shafts greased Fit with ISO H7 tolerance with parallel keyway: according to DIN 6885 Sheet 1	See chapter 4.6.3
<b>Radial shaft seal ring</b>	NBR, form A	See chapter 4.8
<b>Ambient temperature</b>	-10°C to +90°C. The values of the performance tables are valid for +20°C	See chapter 4.9.3
<b>Circumferential backlash</b>	< 20 arcmin	See chapter 11.5.11
<b>Protection class</b>	IP 54	See chapter 4.5
<b>Corrosion protection</b>	Prime coat; layer thickness > 40 µm	See chapter 4.4.1
<b>Bearing life L10h</b>	more than 15,000h	See chapter 4.9.1
<b>Oil change intervals</b>	Not required if the oil temperature is kept < 90°C The lifetime of the bearings can be increased by the factor 1.5 if the oil is changed after the first 500 service hours and then every 5000 service hours.	See chapter 11.5.9
<b>Lubricants</b>	Synthetic lubricants	See chapter 11.5.9
<b>Motor flange</b>	Aluminium	See chapter 11.5.14
<b>Coupling</b>	Insertable, flexible claw coupling, suitable for servo-motors For smooth motor shafts      clamping hub      KN For smooth motor shafts      tension ring hub      SN For motor shafts with parallel key clamping hub with groove      KNN	See chapter 11.5.13

Table 9-13

## Torques in operating mode S1

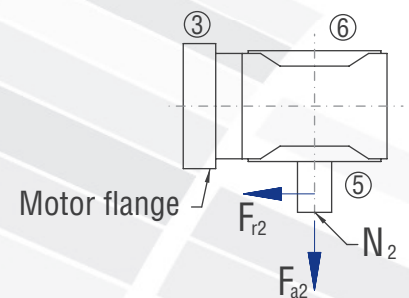
I rated I ist	10:1		20:1	
	$n_2$ [1/min]	$T_{2N}$ [Nm]	$n_2$ [1/min]	$T_{2N}$ [Nm]
4000	410	101	205	116
3000	308	124	154	141
2400	246	148	123	166
1500	154	171	77	190

## Torques in operating mode S5

Coupling size	d [mm]	I rated $T_{2N}$ [Nm] $n_{1max}$ [U/min]	10:1		20:1	
			KN	KNN/SN	KN	KNN/SN
K19	9	$T_{2B}$ [Nm]	165,8		259,0	
		$T_{2NOT}$ [Nm]	292,5		355,0	
	11	$T_{2B}$ [Nm]	165,8	165,8	259,0	259,0
		$T_{2NOT}$ [Nm]	292,5	292,5	355,0	355,0
	14	$T_{2B}$ [Nm]	165,8	165,8	259,0	259,0
		$T_{2NOT}$ [Nm]	306,0	306,0	355,0	355,0
	16	$T_{2B}$ [Nm]	165,8	165,8	259,0	259,0
		$T_{2NOT}$ [Nm]	306,0	306,0	355,0	355,0
	19	$T_{2B}$ [Nm]	165,8	165,8	259,0	259,0
		$T_{2NOT}$ [Nm]	306,0	306,0	355,0	355,0
	24	$T_{2B}$ [Nm]	165,8		259,0	
		$T_{2NOT}$ [Nm]	306,0		355,0	
K24	11	$T_{2B}$ [Nm]	216,0	216,0	259,0	259,0
		$T_{2NOT}$ [Nm]	306,0	0,0	355,0	0,0
	14	$T_{2B}$ [Nm]	216,0	216,0	259,0	259,0
		$T_{2NOT}$ [Nm]	306,0	306,0	355,0	355,0
	16	$T_{2B}$ [Nm]	216,0	216,0	259,0	259,0
		$T_{2NOT}$ [Nm]	306,0	306,0	355,0	355,0
	19	$T_{2B}$ [Nm]	216,0	216,0	259,0	259,0
		$T_{2NOT}$ [Nm]	306,0	306,0	355,0	355,0
	24	$T_{2B}$ [Nm]	216,0	216,0	259,0	259,0
		$T_{2NOT}$ [Nm]	306,0	306,0	355,0	355,0
	28	$T_{2B}$ [Nm]	216,0	216,0	259,0	259,0
		$T_{2NOT}$ [Nm]	306,0	306,0	355,0	355,0

## Permissible radial force $F_{r2}$ and axial force $F_{a2}$ on shaft $N_2$

$n_2$ [rpm]	200		125		75		50		30		10	
$T_2$ [Nm]	$F_r$ [N]	$F_a$ [N]	$F_r$ [N]	$F_a$ [N]	$F_r$ [N]	$F_a$ [N]	$F_r$ [N]	$F_a$ [N]	$F_r$ [N]	$F_a$ [N]	$F_r$ [N]	$F_a$ [N]
< 220	2700	1350	3150	1575	3800	1900	4500	2250	5200	2600	5200	2600
> 220	2080	1040	2420	1210	2920	1460	3460	1730	4000	2000	4000	2000



## Gearbox inertia moments/mass

Inertia moment  $J_1$  related to the fast-rotating shaft ( $N_1$ )

i rated [-]	Inertia moment [kgcm <sup>2</sup> ]						
	5:1	7.5:1	10:1	13:1	15:1	20:1	26:1
$J$ [kgcm <sup>2</sup> ]	2.1678	1.6423	1.1366	0.9368	1.3270	0.9445	0.8175

Mass ca. [kg]
20

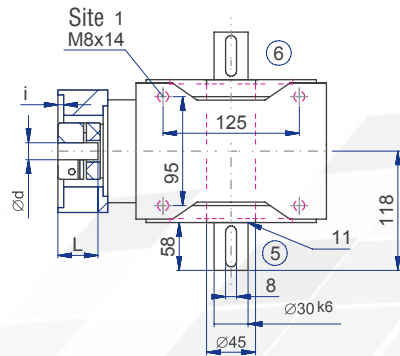
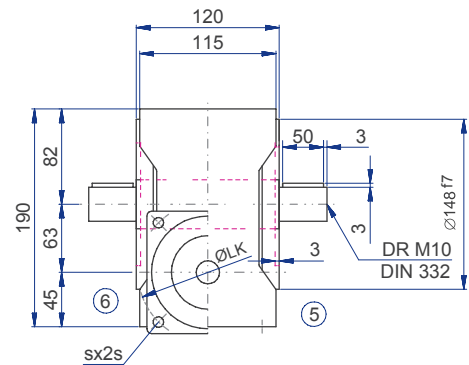
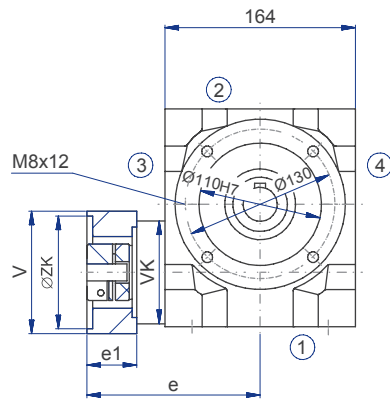
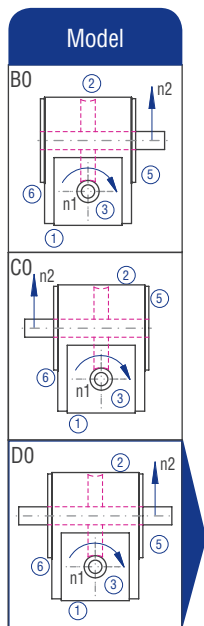
## Inertia moments Coupling J

	KN	KNN	SN
	J [kgcm <sup>2</sup> ]	J [kgcm <sup>2</sup> ]	J [kgcm <sup>2</sup> ]
K19	0.4229	0.4229	0.6349
K24	1.0910	1.0910	2.7750

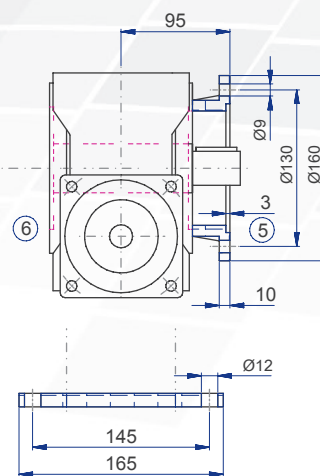
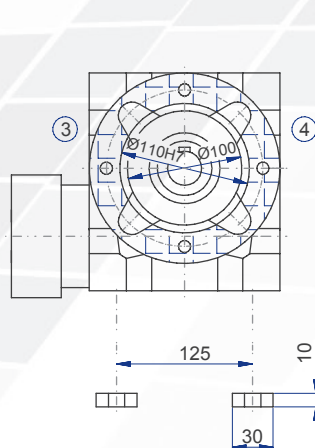
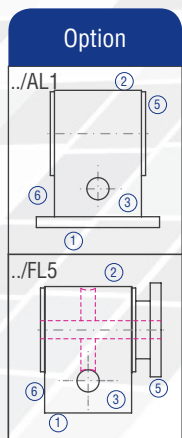
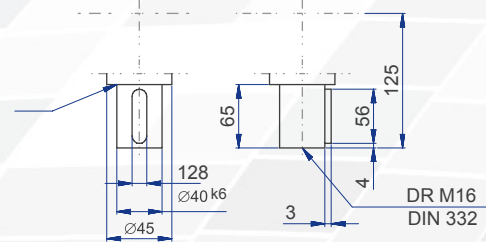
The mass of the gearbox may deviate depending on the flange size and the gear ratio.

Servo gearboxes  
(precision gearboxes)

# 11.5.18 Type SC 063 – Servo worm gearboxes



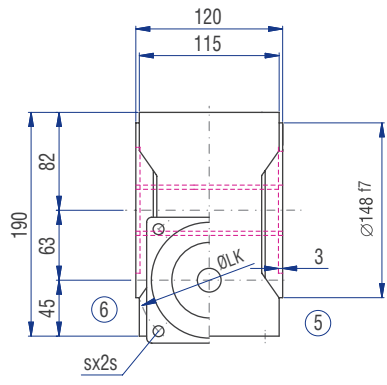
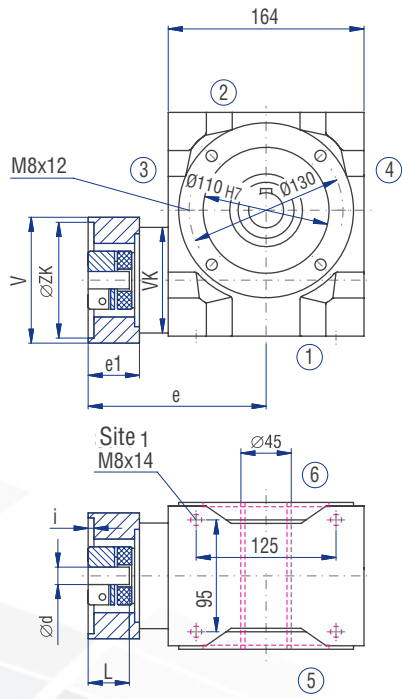
## Implementation VV



## Motor dimensions

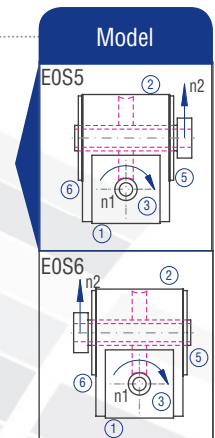
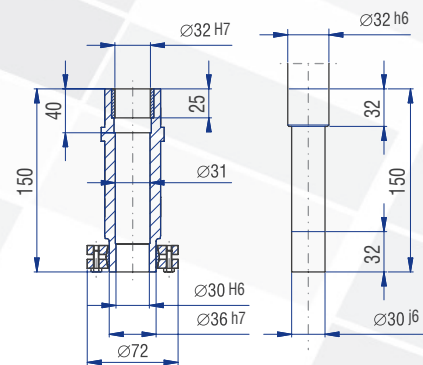
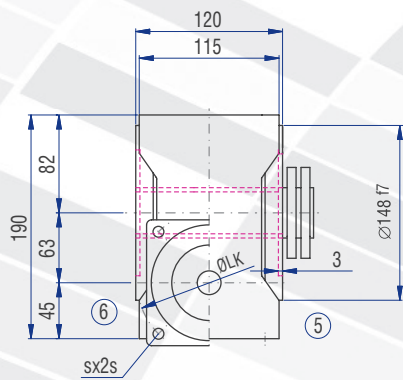
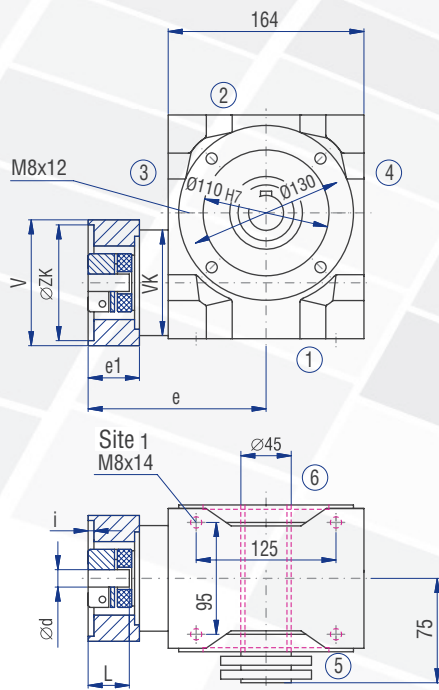
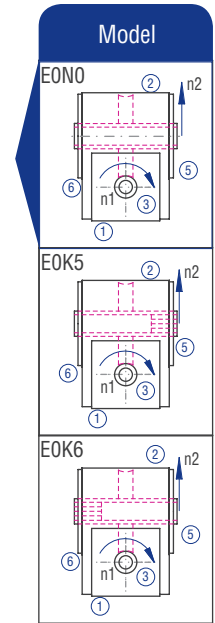
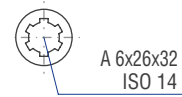
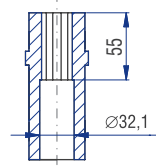
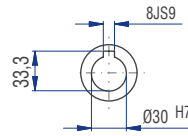
Flange no.	Motor shaft (dxL)	Thread (s)	V [mm]	ZK [mm]	LK [mm]	i [mm]	e [mm]	e1 [mm]
103	19*40	M6	90	60	75	3	154.0	45.0
201	19*40	M5	90	60	90	3	154.0	45.0
301	19*40	M6	90	50	95	4	154.0	45.0
401	19*40	M6	90	80	100	4	154.0	45.0
501	19*40	M8	90	95	115	4	154.0	45.0
601	19*40	M8	90	95	130	4	154.0	45.0
611	19*40	M8	90	110	130	5	154.0	45.0
701	19*40	M8	90	110	145	5	154.0	45.0
802	19*40	M10	90	110	165	5	154.0	45.0
811	24*50	M10	120	130	165	5	177.0	54.0

The dimensions e and e1 will change for the coupling type “clamping hub with groove” (KNN). Please contact us for consultation!



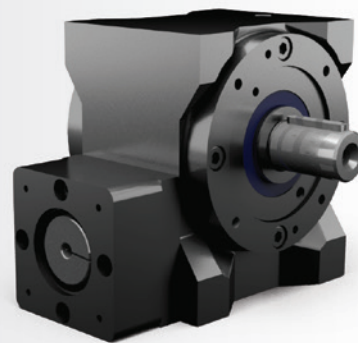
EON0

EOK5 / EOK6



Servo gearboxes  
(precision gearboxes)





## Characteristics

Characteristic	Standard	Option
<b>Toothing</b>	Hardened and ground worm shaft / bronze worm gear	See chapter 11.5.2
<b>Gear ratio</b>	10:1 to 20:1	
<b>Housing / Flanges</b>	Grey cast iron / aluminium	
<b>Threaded mounting holes</b>	On gearbox side 1 and on the flanges	See chapter 11.5.4
<b>Shaft</b>	Material 1 C45, shaft ends greased Fit with ISO j6 tolerance with parallel keyway: according to DIN 6885 Sheet 1	See chapter 4.6.2
<b>Hollow shaft</b>	Material 1 C45, shafts greased Fit with ISO H7 tolerance with parallel keyway: according to DIN 6885 Sheet 1	See chapter 4.6.3
<b>Radial shaft seal ring</b>	NBR, form A	See chapter 4.8
<b>Ambient temperature</b>	-10°C to +90°C. The values of the performance tables are valid for +20°C	See chapter 4.9.3
<b>Circumferential backlash</b>	< 20 arcmin	See chapter 11.5.11
<b>Protection class</b>	IP 54	See chapter 4.5
<b>Corrosion protection</b>	Prime coat; layer thickness > 40 µm	See chapter 4.4.1
<b>Bearing life L10h</b>	more than 15,000h	See chapter 4.9.1
<b>Oil change intervals</b>	Not required if the oil temperature is kept < 90°C The lifetime of the bearings can be increased by the factor 1.5 if the oil is changed after the first 500 service hours and then every 5000 service hours.	See chapter 11.5.9
<b>Lubricants</b>	Synthetic lubricants	See chapter 11.5.9
<b>Motor flange</b>	Aluminium	See chapter 11.5.14
<b>Coupling</b>	Insertable, flexible claw coupling, suitable for servo-motors For smooth motor shafts      clamping hub      KN For smooth motor shafts      tension ring hub      SN For motor shafts with parallel key clamping hub with groove      KNN	See chapter 11.5.13

## Torques in operating mode S1

I rated I ist	10:1		20:1	
	$n_2$ [1/min]	$T_{2N}$ [Nm]	$n_2$ [1/min]	$T_{2N}$ [Nm]
4000	400	132	200	153
3000	300	177	150	203
2400	240	222	120	253
1500	150	267	75	303

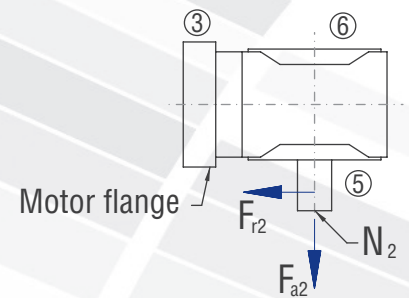
## Torques in operating mode S5

Coupling size	d [mm]	I rated $T_{2N}$ [Nm] $n_{1max}$ [U/min]	10:1		20:1		
			KN	KNN/SN	KN	KNN/SN	
K24	11	$T_{2B}$ [Nm]	350,0	408,0	498,0	498,0	
		$T_{2NOT}$ [Nm]	450,0	0,0	725,0	0,0	
	14	$T_{2B}$ [Nm]	360,0	408,0	498,0	498,0	
		$T_{2NOT}$ [Nm]	450,0	625,0	725,0	725,0	
	16	$T_{2B}$ [Nm]	390,0	408,0	498,0	498,0	
		$T_{2NOT}$ [Nm]	500,0	625,0	725,0	725,0	
	19	$T_{2B}$ [Nm]	390,0	408,0	498,0	498,0	
		$T_{2NOT}$ [Nm]	600,0	625,0	725,0	725,0	
	24	$T_{2B}$ [Nm]	408,0	408,0	498,0	498,0	
		$T_{2NOT}$ [Nm]	625,0	625,0	725,0	725,0	
	28	$T_{2B}$ [Nm]	408,0	408,0	498,0	498,0	
		$T_{2NOT}$ [Nm]	625,0	625,0	725,0	725,0	
	K28	14	$T_{2B}$ [Nm]	408,0		498,0	
			$T_{2NOT}$ [Nm]	625,0		725,0	
16		$T_{2B}$ [Nm]	408,0	408,0	498,0	498,0	
		$T_{2NOT}$ [Nm]	625,0	625,0	725,0	725,0	
19		$T_{2B}$ [Nm]	408,0	408,0	498,0	498,0	
		$T_{2NOT}$ [Nm]	625,0	625,0	725,0	725,0	
24		$T_{2B}$ [Nm]	408,0	408,0	498,0	498,0	
		$T_{2NOT}$ [Nm]	625,0	625,0	725,0	725,0	
28		$T_{2B}$ [Nm]	408,0	408,0	498,0	498,0	
		$T_{2NOT}$ [Nm]	625,0	625,0	725,0	725,0	
32		$T_{2B}$ [Nm]	408,0	408,0	498,0	498,0	
		$T_{2NOT}$ [Nm]	625,0	625,0	725,0	725,0	
38		$T_{2B}$ [Nm]	408,0	408,0	498,0	498,0	
		$T_{2NOT}$ [Nm]	625,0	0,0	725,0	0,0	

Servo gearboxes  
(precision gearboxes)

## Permissible radial force $F_{r2}$ and axial force $F_{a2}$ on shaft $N_2$

$n_2$ [rpm]	200		125		75		50		30		10	
$T_2$ [Nm]	$F_r$ [N]	$F_a$ [N]	$F_r$ [N]	$F_a$ [N]	$F_r$ [N]	$F_a$ [N]	$F_r$ [N]	$F_a$ [N]	$F_r$ [N]	$F_a$ [N]	$F_r$ [N]	$F_a$ [N]
< 430	3300	1650	3750	1875	4500	2250	5300	2650	6300	3150	7600	3800
> 430	2640	1320	3000	1500	3600	1800	4240	2120	5040	2520	6080	3040



## Gearbox inertia moments/mass

Inertia moment  $J_1$  related to the fast-rotating shaft ( $N_1$ )

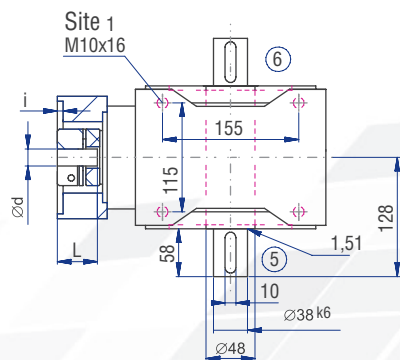
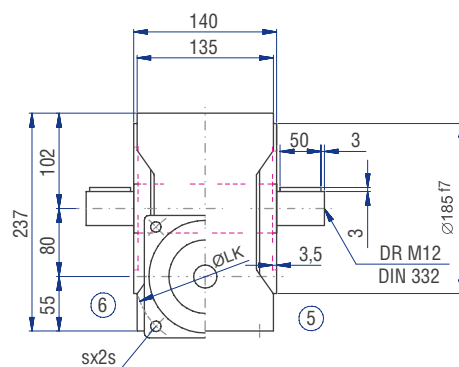
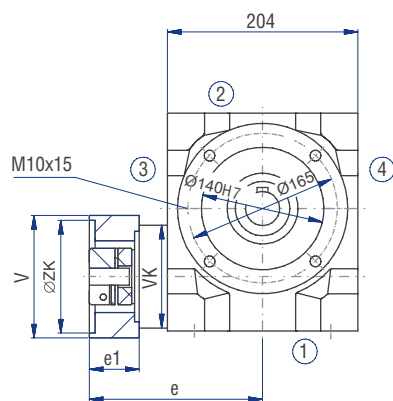
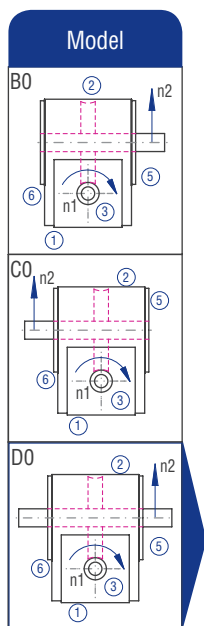
i rated [-]	Inertia moment [kgcm <sup>2</sup> ]							Mass ca. [kg]
	5:1	7.5:1	10:1	13:1	15:1	20:1	26:1	
$J$ [kgcm <sup>2</sup> ]	5.8195	4.2167	2.9560	2.2634	3.2550	2.3977	1.9066	30

## Inertia moments Coupling J

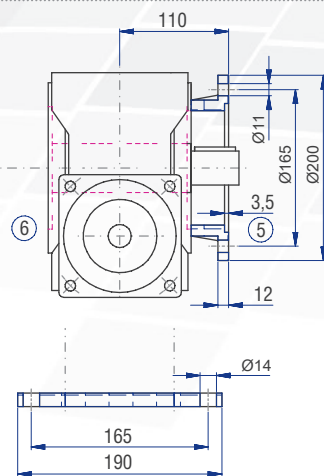
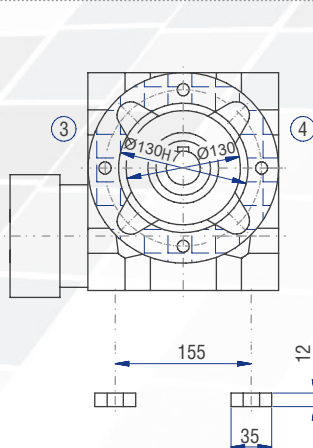
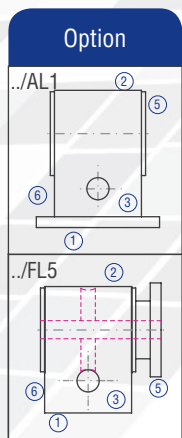
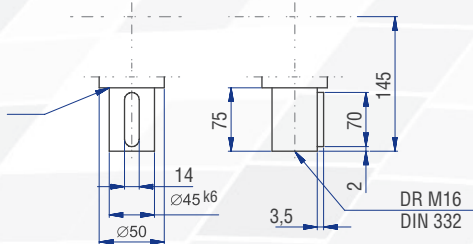
	KN	KNN	SN
	J [kgcm <sup>2</sup> ]	J [kgcm <sup>2</sup> ]	J [kgcm <sup>2</sup> ]
K24	1.0910	1.0910	2.7750
K28	4.1710	4.1710	6.4250

The mass of the gearbox may deviate depending on the flange size and the gear ratio.

# 11.5.19 Type SC 080 – Servo worm gearboxes



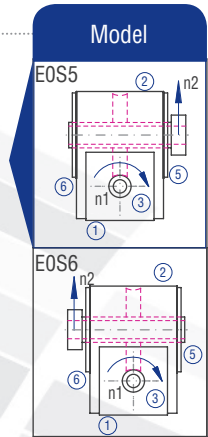
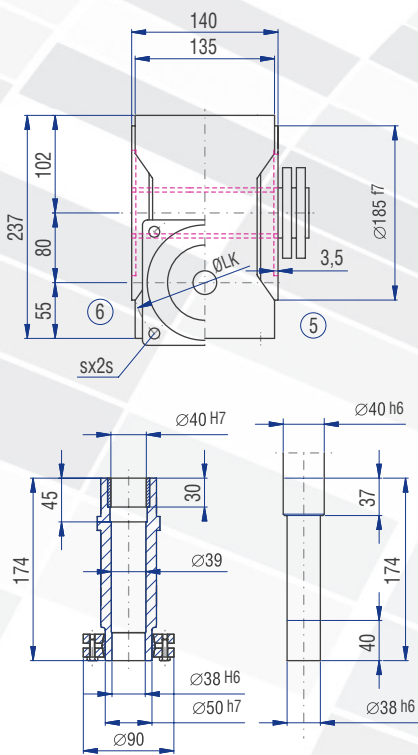
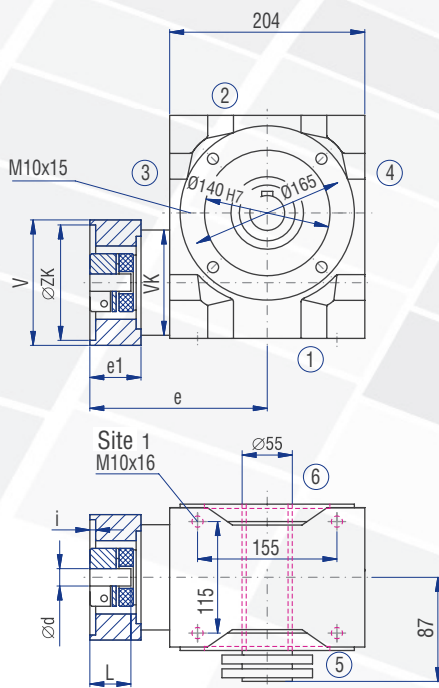
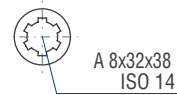
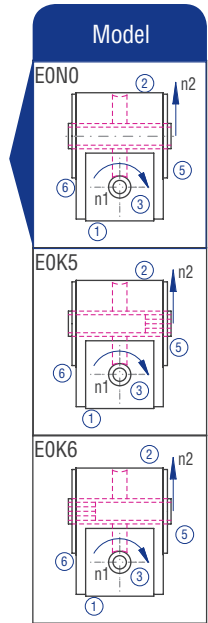
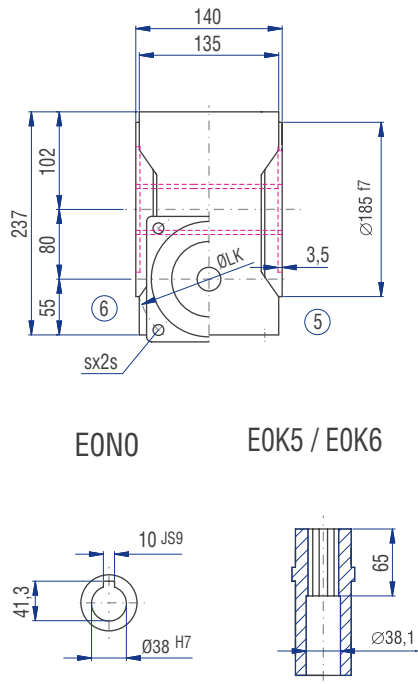
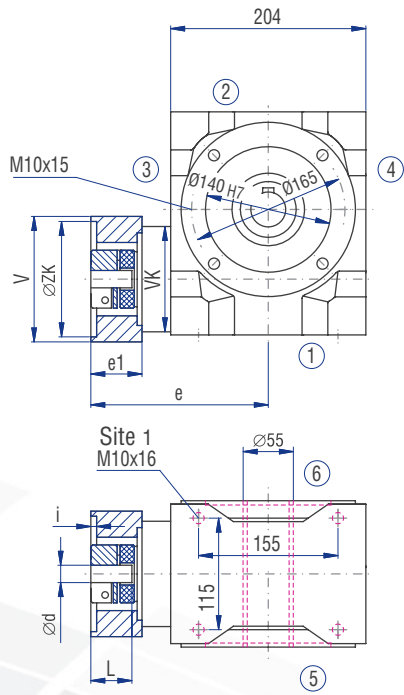
## Implementation VV



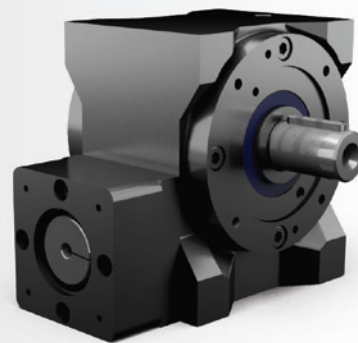
## Motor dimensions

Flange no.	Motor shaft (dxL)	Thread (s)	V [mm]	ZK [mm]	LK [mm]	i [mm]	e [mm]	e1 [mm]
103	24*50	M6	120	60	75	3	192.5	54.0
201	24*50	M5	120	60	90	3	192.5	54.0
301	24*50	M6	120	50	95	4	192.5	54.0
401	24*50	M6	120	80	100	4	192.5	54.0
501	24*50	M8	120	95	115	4	192.5	54.0
601	24*50	M8	120	95	130	4	192.5	54.0
611	24*50	M8	120	110	130	5	192.5	54.0
701	24*50	M8	120	110	145	5	192.5	54.0
802	24*50	M10	120	110	165	5	192.5	54.0
811	24*50	M10	120	130	165	5	192.5	54.0
403	32*60	M6	140	80	100	4	202.5	61.0
502	32*60	M8	140	95	115	4	202.5	61.0
616	32*60	M10	140	110	130	5	202.5	61.0
902	32*60	M12	140	130	215	6	202.5	61.0
911	32*60	M12	140	180	215	6	202.5	61.0
932	38*80	M12	160	180	215	6	241.0	99.5

The dimensions e and e1 will change for the coupling type "clamping hub with groove" (KNN). Please contact us for consultation!



Servo gearboxes  
(precision gearboxes)



## Characteristics

Characteristic	Standard	Option
<b>Toothing</b>	Hardened and ground worm shaft / bronze worm gear	See chapter 11.5.2
<b>Gear ratio</b>	10:1 to 20:1	
<b>Housing / Flanges</b>	Grey cast iron / aluminium	
<b>Threaded mounting holes</b>	On gearbox side 1 and on the flanges	See chapter 11.5.4
<b>Shaft</b>	Material 1 C45, shaft ends greased Fit with ISO j6 tolerance with parallel keyway: according to DIN 6885 Sheet 1	See chapter 4.6.2
<b>Hollow shaft</b>	Material 1 C45, shafts greased Fit with ISO H7 tolerance with parallel keyway: according to DIN 6885 Sheet 1	See chapter 4.6.3
<b>Radial shaft seal ring</b>	NBR, form A	See chapter 4.8
<b>Ambient temperature</b>	-10°C to +90°C. The values of the performance tables are valid for +20°C	See chapter 4.9.3
<b>Circumferential backlash</b>	< 20 arcmin	See chapter 11.5.11
<b>Protection class</b>	IP 54	See chapter 4.5
<b>Corrosion protection</b>	Prime coat; layer thickness > 40 µm	See chapter 4.4.1
<b>Bearing life L10h</b>	more than 15,000h	See chapter 4.9.1
<b>Oil change intervals</b>	Not required if the oil temperature is kept < 90°C The lifetime of the bearings can be increased by the factor 1.5 if the oil is changed after the first 500 service hours and then every 5000 service hours.	See chapter 11.5.9
<b>Lubricants</b>	Synthetic lubricants	See chapter 11.5.9
<b>Motor flange</b>	Aluminium	See chapter 11.5.14
<b>Coupling</b>	Insertable, flexible claw coupling, suitable for servo-motors For smooth motor shafts      clamping hub      KN For smooth motor shafts      tension ring hub      SN For motor shafts with parallel key clamping hub with groove      KNN	See chapter 11.5.13

## Torques in operating mode S1

I rated I ist	10:1		20:1	
	$n_2$ [1/min]	$T_{2N}$ [Nm]	$n_2$ [1/min]	$T_{2N}$ [Nm]
4000	400	132	200	153
3000	300	177	150	203
2400	240	222	120	253
1500	150	267	75	303

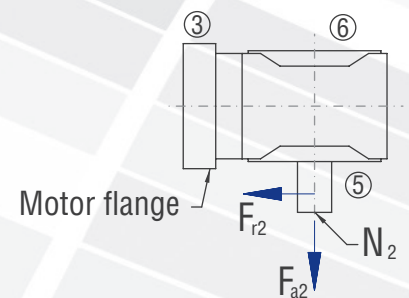
## Torques in operating mode S5

Coupling size	d [mm]	I rated $T_{2N}$ [Nm] $n_{1max}$ [U/min]	10:1		20:1		
			KN	KNN/SN	KN	KNN/SN	
K24	11	$T_{2B}$ [Nm]	350,0	408,0	498,0	498,0	
		$T_{2NOT}$ [Nm]	450,0	0,0	725,0	0,0	
	14	$T_{2B}$ [Nm]	360,0	408,0	498,0	498,0	
		$T_{2NOT}$ [Nm]	450,0	625,0	725,0	725,0	
	16	$T_{2B}$ [Nm]	390,0	408,0	498,0	498,0	
		$T_{2NOT}$ [Nm]	500,0	625,0	725,0	725,0	
	19	$T_{2B}$ [Nm]	390,0	408,0	498,0	498,0	
		$T_{2NOT}$ [Nm]	600,0	625,0	725,0	725,0	
	24	$T_{2B}$ [Nm]	408,0	408,0	498,0	498,0	
		$T_{2NOT}$ [Nm]	625,0	625,0	725,0	725,0	
	28	$T_{2B}$ [Nm]	408,0	408,0	498,0	498,0	
		$T_{2NOT}$ [Nm]	625,0	625,0	725,0	725,0	
	K28	14	$T_{2B}$ [Nm]	408,0		498,0	
			$T_{2NOT}$ [Nm]	625,0		725,0	
16		$T_{2B}$ [Nm]	408,0	408,0	498,0	498,0	
		$T_{2NOT}$ [Nm]	625,0	625,0	725,0	725,0	
19		$T_{2B}$ [Nm]	408,0	408,0	498,0	498,0	
		$T_{2NOT}$ [Nm]	625,0	625,0	725,0	725,0	
24		$T_{2B}$ [Nm]	408,0	408,0	498,0	498,0	
		$T_{2NOT}$ [Nm]	625,0	625,0	725,0	725,0	
28		$T_{2B}$ [Nm]	408,0	408,0	498,0	498,0	
		$T_{2NOT}$ [Nm]	625,0	625,0	725,0	725,0	
32		$T_{2B}$ [Nm]	408,0	408,0	498,0	498,0	
		$T_{2NOT}$ [Nm]	625,0	625,0	725,0	725,0	
38		$T_{2B}$ [Nm]	408,0	408,0	498,0	498,0	
		$T_{2NOT}$ [Nm]	625,0	0,0	725,0	0,0	

Servo gearboxes  
(precision gearboxes)

## Permissible radial force $F_{r2}$ and axial force $F_{a2}$ on shaft $N_2$

$n_2$ [rpm]	200		125		75		50		30		10	
$T_2$ [Nm]	$F_r$ [N]	$F_a$ [N]	$F_r$ [N]	$F_a$ [N]	$F_r$ [N]	$F_a$ [N]	$F_r$ [N]	$F_a$ [N]	$F_r$ [N]	$F_a$ [N]	$F_r$ [N]	$F_a$ [N]
< 800	3650	1825	4000	2000	4750	2375	5600	2800	6700	3350	9500	4750
> 800	2920	1460	3200	1600	3800	1900	4480	2240	5360	2680	7600	3800



## Gearbox inertia moments/mass

Inertia moment  $J_1$  related to the fast-rotating shaft ( $N_1$ )

i rated [-]	Inertia moment [kgcm <sup>2</sup> ]						
	5:1	7.5:1	10:1	13:1	15:1	20:1	26:1
$J$ [kgcm <sup>2</sup> ]	22.3780	17.8750	14.0300	12.2840	15.1730	12.3740	11.3360

Mass ca. [kg]
53

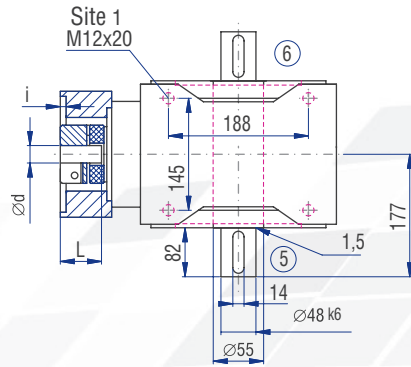
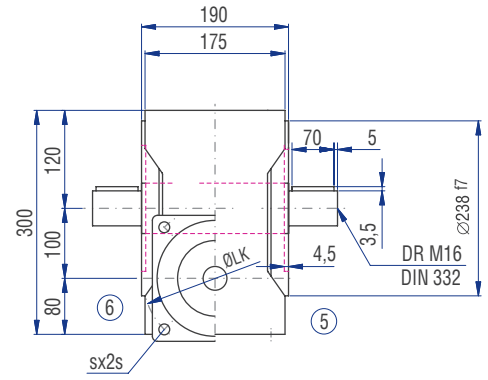
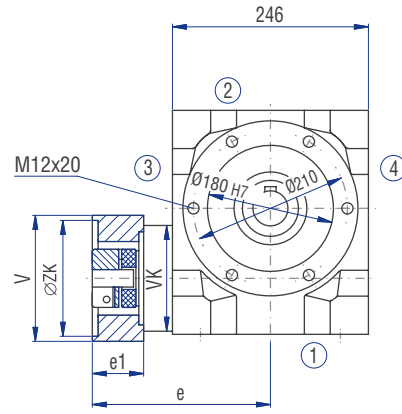
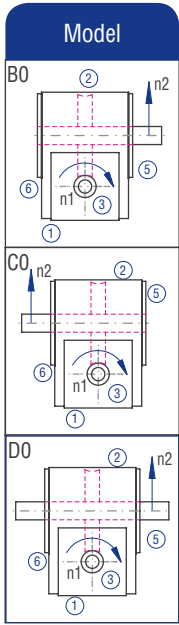
## Inertia moments Coupling J

K38	KN	KNN	SN
	J [kgcm <sup>2</sup> ]	J [kgcm <sup>2</sup> ]	J [kgcm <sup>2</sup> ]
	4.1710	4.1710	6.4250
	8.4580	8.4580	19.6460

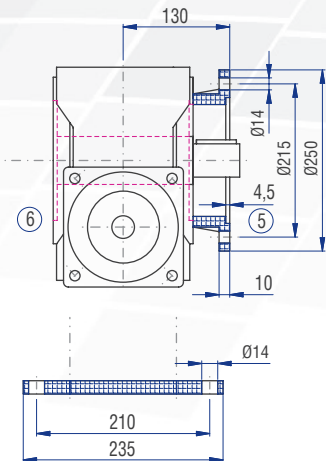
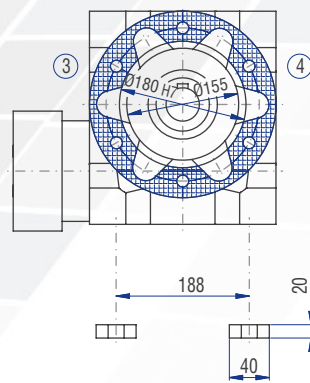
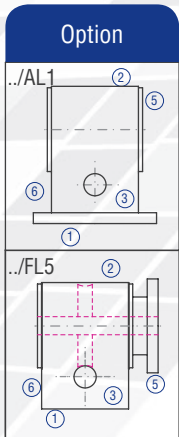
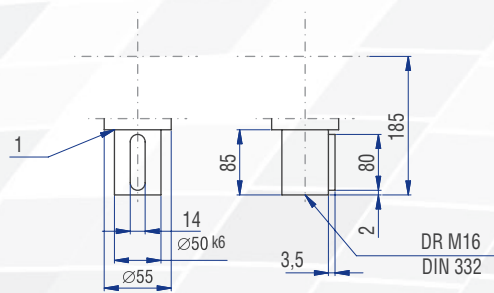
The mass of the gearbox may deviate depending on the flange size and the gear ratio.



# 11.5.20 Type SC 100 – Servo worm gearboxes



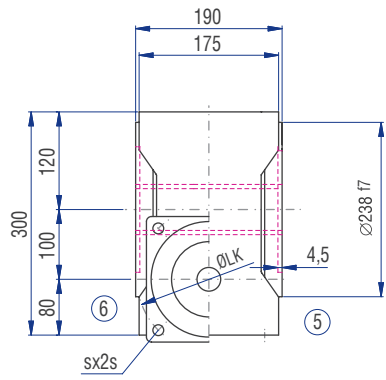
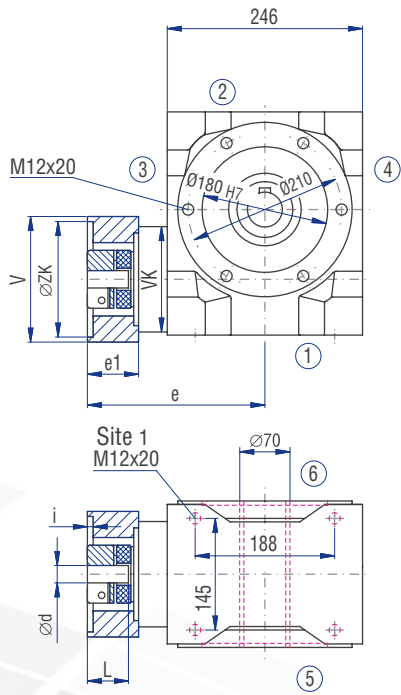
## Implementation VV



## Motor dimensions

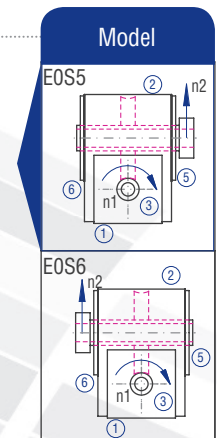
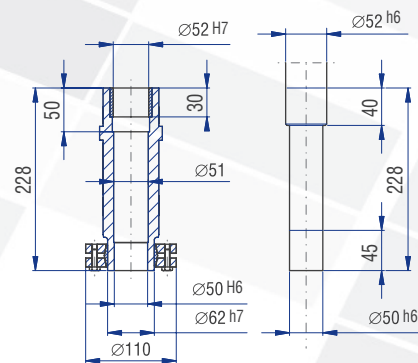
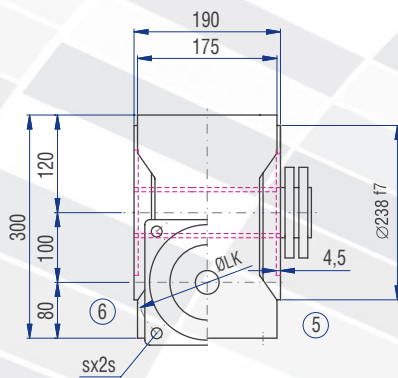
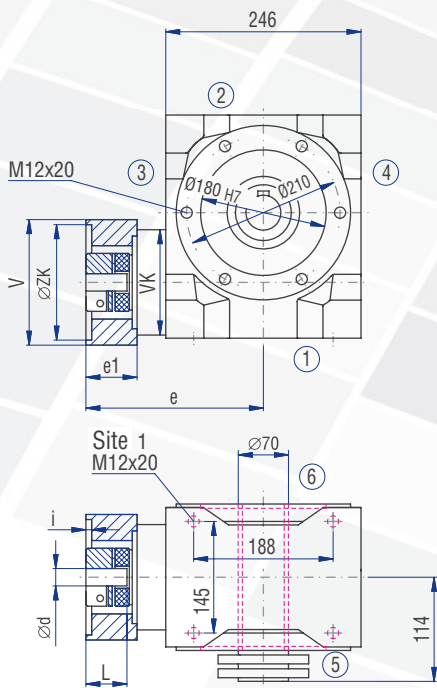
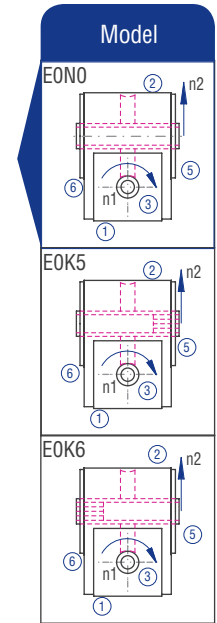
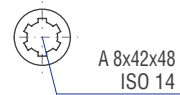
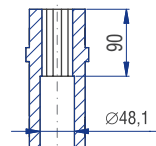
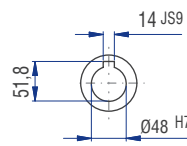
Flange no.	Motor shaft (dxL)	Thread (s)	V [mm]	ZK [mm]	LK [mm]	i [mm]	e [mm]	e1 [mm]
601	32*60	M8	160	95	130	4	242.0	62.0
611	32*60	M8	160	110	130	5	242.0	62.0
701	32*60	M8	160	110	145	5	242.0	62.0
802	32*60	M10	160	110	165	5	242.0	62.0
811	32*60	M10	160	130	165	5	242.0	62.0
403	32*60	M6	160	80	100	4	242.0	62.0
502	32*60	M8	160	95	115	4	242.0	62.0
616	32*60	M10	160	110	130	5	242.0	62.0
902	32*60	M12	160	130	215	6	242.0	62.0
911	32*60	M12	160	180	215	6	242.0	62.0

The dimensions e and e1 will change for the coupling type "clamping hub with groove" (KNN). Please contact us for consultation!



EON0

EOK5 / EOK6



Servo gearboxes  
(precision gearboxes)